

## Ph.D. Requirements (minimum total of 30 credits post-M.S., 47 credits for post B.S. students))

### Core Course Requirement - 12 Credits

- Robotics Mechanics Core Area*  
ROBOT 6000 Robotics I: Mechanics | 3 Credits
- Robot Control Core Area*  
ROBOT 6100 Robotics II: Control | 3 Credits
- Cognition Core Area (Pick One)*  
ROBOT 6200 Motion Planning | 3 Credits (spring)  
CS 6300 | Artificial Intelligence | 3 Credits (fall)
- Perception Core Area (Pick One)*  
CS 6640 | Image Processing | 3 Credits (fall)  
CS 6320 | Computer Vision | 3 Credits (fall)

### Elective Course Requirement \* 9 Credits

- Select 3 classes from two different categories

### Allied Courses \*\* 9-10 Credits

- Remaining courses to reach the 30-credit hour coursework minimum requirement

### Seminar Requirement 3 Credits

- Department Seminar | 1 Credit*  
ME EN 6890 OR ECE 6900-001 OR CS 7930-001  
(Enroll in the seminar associated with your thesis advisor)
- ROBOT 6800 Robotics Seminar | 2 Credits*  
(Enroll in 2 semesters for 1 credit each semester)

### Dissertation Requirement \*\*\* 14 Credits

- ROBOT 7970 Ph.D. Dissertation | 14 Credits (Advisors' section)*

### Elective Course Requirement \* 9 Cr

Select 3 classes from **two** categories

#### *Robot Mechanics Category Electives*

- ROBOT 7000 Manipulation and Mobility
- ROBOT 7010 System Identification for Robotics

#### *Robot Control Category Electives*

- ME EN 6200 OR ECE 6615 |  
Classical Control Systems
- ECE 6670 | Control of Electric Motors
- ME EN 6210 OR ECE 6652 OR  
CH EN 6203 | State Space Control
- ME EN 7200 | Nonlinear Control
- ME EN 7210 | Optimal Control
- ECE 6570 | Adaptive Control

#### *Cognition Category*

- CS 6350 | Machine Learning
- CS 6958 | Robot Learning

#### *Perception Category*

- CS 7640 | Advanced Image Processing
- CS 6353 | Deep Learning for  
Image Analysis

#### *Human-Robot Interaction Category*

- CS 6360 | Virtual Reality
- ROBOT 7400 Haptics for VR,  
Teleoperation, and Physical  
Human-Robot Interaction
- ROBOT 6400 Neural Engineering and  
NeuroRobotics

#### *Robot Design Category*

- ROBOT 6500 Advanced Mechatronics
- ROBOT 6960 | Wearable Robotics
- ECE 6780 OR CS 6780 | Embedded  
System Design
- ECE 6960 | Robotic Millisystems
- CS 6956 | Medical Robotics

#### *Other Supporting Elective Category*

- ME EN 6035 | Design of Experiments
- ME EN 6100 | Ergonomics
- ECE 6540 | Estimation Theory
- CS 6540 | Human-Computer Interaction
- ME EN 6410 | Intermediate Dynamics
- CS 6340 | Natural Language Processing
- ME EN 6205 | System Dynamics

All electives are 3 credits, with the exception of ROBOT 6400, 6500, ECE/CS 6780 (which are each 4 credits).

Core courses not used to fulfill a core area requirement may also be considered.

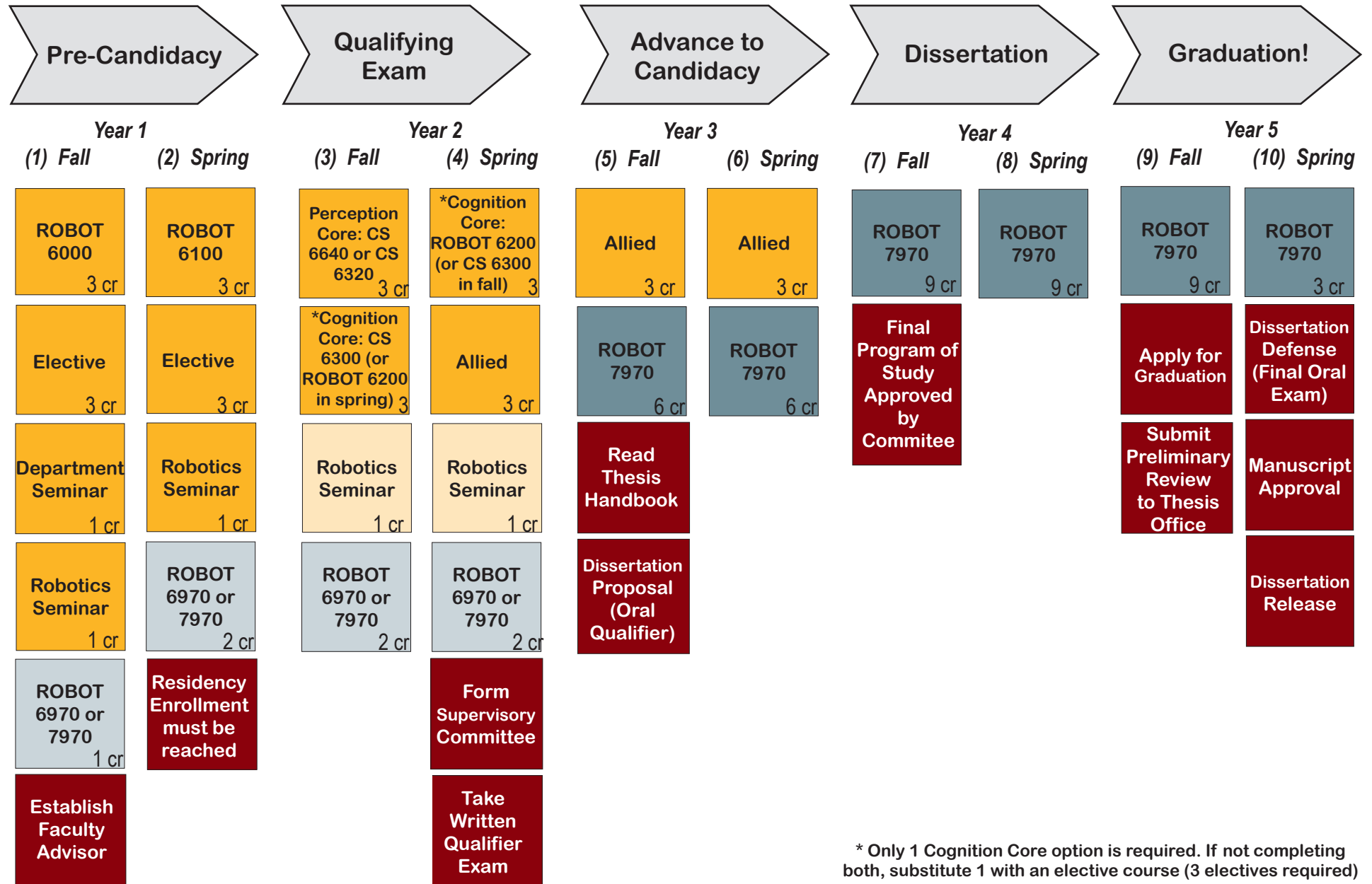
### Allied Courses \*\* 9-10 Credits

Remaining courses to reach the 30-credit hour coursework minimum requirement may be chosen from core courses, preapproved electives, supporting electives, lecture-based engineering/science courses (e.g., excluding seminars, projects, thesis), or approved non-engineering/science courses. Subject to supervisory committee approval.

**Example Program of Study for an Ph.D. (Post-B.S.) in Robotics**

Below is one possibility for a program of study that satisfies the Ph.D. degree and milestone requirements. At least 9 credits per semester is required to qualify for tuition benefit. Course selections may change based on faculty advisement.

Course Work	Research	Required Milestone	Optional	Post-BS =6970 Post-MS = 7970
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\* Only 1 Cognition Core option is required. If not completing both, substitute 1 with an elective course (3 electives required)